GENERAL DESCRIPTION

The AKD4627-A is an evaluation board for the AK4627, a single chip CODEC that includes four channels of ADC and six channels of DAC. The AKD4627-A also has the digital audio interface and can achieve the interface with digital audio systems via opt-connector or BNC connector.

Ordering guide

AKD4627-A --- AK4627 Evaluation Board  
(Cable for connecting with printer port of IBM-AT compatible PC and control software are packed with this.) This control software can't operate on Windows NT.

FUNCTION

- On-board analog output buffer circuit
- Compatible with 2 types of interface
  - AK4118 (DIT&DIR) with optical output/input and BNC output/input
  - Direct interface with AC3 decoder by 10pin header
- 10pin header for serial control interface

![AKD4627-A Block Diagram](image)

*Circuit diagram and PCB layout are attached at the end of this manual.
**Operation sequence**

1) Set up the power supply lines.

(1-1) In case of using separate power supply lines <Default>

Set up the jumper pins.

```
<table>
<thead>
<tr>
<th>JP82</th>
<th>JP83</th>
<th>JP84</th>
</tr>
</thead>
<tbody>
<tr>
<td>AVDD</td>
<td>DVDD</td>
<td>TVDD</td>
</tr>
<tr>
<td>REG</td>
<td>JACK</td>
<td>REG</td>
</tr>
</tbody>
</table>
```

Set up the power supply lines.

<table>
<thead>
<tr>
<th>Name</th>
<th>Color</th>
<th>Voltage</th>
<th>Comments</th>
<th>Attention</th>
</tr>
</thead>
<tbody>
<tr>
<td>+12V</td>
<td>Red</td>
<td>+12V</td>
<td>Regulator, Power Supply for Op-amp</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>-12V</td>
<td>Red</td>
<td>-12V</td>
<td>Power Supply for Op-amp</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>AVDD</td>
<td>Orange</td>
<td>+5V</td>
<td>Power supply for AVDD of the AK4627</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>DVDD</td>
<td>Orange</td>
<td>+5V</td>
<td>Power supply for DVDD of the AK4627</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>TVDD</td>
<td>Orange</td>
<td>+5V</td>
<td>Power supply for TVDD of the AK4627</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>AGND</td>
<td>Black</td>
<td>0V</td>
<td>Analog ground</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>DGND</td>
<td>Black</td>
<td>0V</td>
<td>Digital ground</td>
<td>Should be connected.</td>
</tr>
</tbody>
</table>

Table 1 Set up of power supply lines

(1-2) In case of using the regulator

Set up the jumper pins.

```
<table>
<thead>
<tr>
<th>JP82</th>
<th>JP83</th>
<th>JP84</th>
</tr>
</thead>
<tbody>
<tr>
<td>AVDD</td>
<td>DVDD</td>
<td>TVDD</td>
</tr>
<tr>
<td>REG</td>
<td>JACK</td>
<td>REG</td>
</tr>
</tbody>
</table>
```

Set up the power supply lines.

<table>
<thead>
<tr>
<th>Name</th>
<th>Color</th>
<th>Voltage</th>
<th>Comments</th>
<th>Attention</th>
</tr>
</thead>
<tbody>
<tr>
<td>+12V</td>
<td>Red</td>
<td>+12V</td>
<td>Regulator, Power Supply for Op-amp</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>-12V</td>
<td>Red</td>
<td>-12V</td>
<td>Power Supply for Op-amp</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>AVDD</td>
<td>Orange</td>
<td>+5V</td>
<td>Power supply for AVDD of the AK4627</td>
<td>Should be open.</td>
</tr>
<tr>
<td>DVDD</td>
<td>Orange</td>
<td>+5V</td>
<td>Power supply for DVDD of the AK4627</td>
<td>Should be open.</td>
</tr>
<tr>
<td>TVDD</td>
<td>Orange</td>
<td>+5V</td>
<td>Power supply for TVDD of the AK4627</td>
<td>Should be open.</td>
</tr>
<tr>
<td>AGND</td>
<td>Black</td>
<td>0V</td>
<td>Analog ground</td>
<td>Should be connected.</td>
</tr>
<tr>
<td>DGND</td>
<td>Black</td>
<td>0V</td>
<td>Digital ground</td>
<td>Should be connected.</td>
</tr>
</tbody>
</table>

Table 2 Set up of power supply lines

2) Set up the evaluation mode, jumper pins. (See the followings)

3) Power on.

The AK4627 and AK4118 should be reset once bringing SW1 “L” upon power-up.
Control mode

(1) Parallel control mode <Default>

(1-1) Set up Parallel/Serial select pin
Set up SW2-7 (PS) to “H”. (See Table 3)

(1-2) Set up the jumper pins

(2) Serial control mode

(1-1) Set up Parallel/Serial select pin
Set up SW2-7 (PS) to “L”. (See Table 3)

(1-2) Set up the jumper pins

Audio I/F evaluation mode

(1) Evaluation of ADC using DIT of AK4118

(1-1) Set up analog inputs

(1-1-1) Evaluation of ADC using DIT of AK4118 when single-ended inputs
PORT2 (DIT) or J2 (BNC_TX) is used. Nothing should be connected to PORT4 (AC3).
Set up SW2-2 (SGL) to H (See Table 3).

Set up the jumper pins.
(1-1-2) Evaluation of ADC using DIT of AK4118 when differential inputs <Default>
PORT2 (DIT) or J2 (BNC_TX) is used. Nothing should be connected to PORT4 (AC3).
Set up SW2-2 (SGL) to L (See Table 3).

Set up the jumper pins.

(1-2) Set up the digital output

(1-2-1) In case of selecting SDTO1 <Default>
Set up the jumper pin.

(1-2-2) In case of selecting SDTO2
Set up the jumper pin.

(1-3) Set up the audio interface.
Set up the jumper pins.
(2) Evaluation of DAC using DIR of AK4118 <Default>

J1 (BNC_RX) or PORT1 (DIR) is used. Nothing should be connected to PORT4 (AC3).

(2-1) Set up the digital inputs

Set up the jumper pins.

<table>
<thead>
<tr>
<th>JP66</th>
<th>JP67</th>
<th>JP68</th>
</tr>
</thead>
<tbody>
<tr>
<td>SDTI1</td>
<td>SDTI2</td>
<td>SDTI3</td>
</tr>
</tbody>
</table>

(2-2) Set up the audio interface

Set up the jumper pins.

<table>
<thead>
<tr>
<th>JP16</th>
<th>JP17</th>
</tr>
</thead>
<tbody>
<tr>
<td>BICK-SEL</td>
<td>LRCK-SEL</td>
</tr>
</tbody>
</table>

(2-3) Set up the SMUTE pin

Set up the jumper pin.

<table>
<thead>
<tr>
<th>JP64</th>
</tr>
</thead>
<tbody>
<tr>
<td>SMUTE</td>
</tr>
</tbody>
</table>

When JP64 (SMUTE) is open, soft mute cycle is initialized. When JP64 (SMUTE) is short, the output mute releases.
DIP Switch set up

[SW2] (MODE1): Mode settings for AK4627.
About the TDM mode of AK4627, please refer to Page 18 of AK4627’s datasheet.

<table>
<thead>
<tr>
<th>No.</th>
<th>Name</th>
<th>&quot;H&quot;</th>
<th>&quot;L&quot;</th>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>TDM0</td>
<td>TDM Mode</td>
<td>Normal Mode</td>
<td>L</td>
</tr>
<tr>
<td>2</td>
<td>SGL</td>
<td>ADC Single-ended Input Mode</td>
<td>ADC Differential Input Mode</td>
<td>L</td>
</tr>
<tr>
<td>3</td>
<td>I2C</td>
<td>I2C Bus</td>
<td>3-wire Serial</td>
<td>L</td>
</tr>
<tr>
<td>4</td>
<td>DFS0</td>
<td>Double Speed</td>
<td>Normal Speed</td>
<td>L</td>
</tr>
<tr>
<td>5</td>
<td>DZFE</td>
<td>Zero Input Detect.</td>
<td>Refer to the datasheet P23 of the AK4627.</td>
<td>L</td>
</tr>
<tr>
<td>6</td>
<td>PS</td>
<td>Parallel Control mode</td>
<td>Serial Control mode</td>
<td>H</td>
</tr>
<tr>
<td>7</td>
<td>CAD1</td>
<td>Chip Address Select.</td>
<td>Refer to Table 9</td>
<td>L</td>
</tr>
<tr>
<td>8</td>
<td>CAD0</td>
<td></td>
<td></td>
<td>L</td>
</tr>
</tbody>
</table>

Table 3 Mode Setting for AK4627

[SW3] (AK4118 Mode_setting): Mode setting for AK4118.

<table>
<thead>
<tr>
<th>No.</th>
<th>Name</th>
<th>&quot;H&quot;</th>
<th>&quot;L&quot;</th>
<th>Default</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>DIF2</td>
<td>AK4118’s Audio Data Format Settings, and AK4627’s Audio Data Format Settings when Parallel Control Mode.</td>
<td>AK4627’s Audio Data Format Settings when Parallel Control Mode.</td>
<td>H</td>
</tr>
<tr>
<td>2</td>
<td>DIF1</td>
<td>AK4627’s Audio Data Format Settings when Parallel Control Mode.</td>
<td>AK4627’s Audio Data Format Settings when Parallel Control Mode.</td>
<td>L</td>
</tr>
<tr>
<td>3</td>
<td>DIF0</td>
<td>Parallel Control Mode. See Table 5 and Table 6</td>
<td>Parallel Control Mode. See Table 5 and Table 6</td>
<td>L</td>
</tr>
<tr>
<td>4</td>
<td>OCKS1</td>
<td>AK4118’s Master Clock Settings.</td>
<td>AK4118’s Master Clock Settings.</td>
<td>H</td>
</tr>
<tr>
<td>5</td>
<td>OCKS0</td>
<td>See Table 7</td>
<td>See Table 7</td>
<td>L</td>
</tr>
<tr>
<td>6</td>
<td>CM1</td>
<td>AK4118’s Clock Operation Mode Select.</td>
<td>AK4118’s Clock Operation Mode Select.</td>
<td>L</td>
</tr>
<tr>
<td>7</td>
<td>CM0</td>
<td>See Table 8</td>
<td>See Table 8</td>
<td>L</td>
</tr>
</tbody>
</table>

Table 4 Mode Setting for AK4118

AK4118’s audio data format and AK4627’s audio data format are set up at the same time by settings of SW3-1 (DIF2), SW3-2 (DIF1) and SW3-3 (DIF0) when AK4627 is on Parallel Control Mode.

<table>
<thead>
<tr>
<th>SW3-1 DIF2</th>
<th>SW3-2 DIF1</th>
<th>SW3-3 DIF0</th>
<th>AK4627 DIF1</th>
<th>AK4627 DIF0</th>
<th>AK4118 DAUX</th>
<th>AK4118 SDTO</th>
<th>LRCK</th>
<th>BICK</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0 0</td>
<td>0 0 0 0 0</td>
<td>24bit, Left justified</td>
<td>20bit, Right justified</td>
<td>H/L</td>
<td>O</td>
<td>64fs</td>
<td>O</td>
<td></td>
</tr>
<tr>
<td>0 0 1 0 0</td>
<td>0 0 0 0 0</td>
<td>24bit, Left justified</td>
<td>20bit, Right justified</td>
<td>H/L</td>
<td>O</td>
<td>64fs</td>
<td>O</td>
<td></td>
</tr>
<tr>
<td>0 0 0 0 0</td>
<td>0 0 0 0 0</td>
<td>24bit, Left justified</td>
<td>20bit, Right justified</td>
<td>H/L</td>
<td>O</td>
<td>64fs</td>
<td>O</td>
<td></td>
</tr>
<tr>
<td>0 0 0 0 0</td>
<td>0 0 0 0 0</td>
<td>24bit, Left justified</td>
<td>20bit, Right justified</td>
<td>H/L</td>
<td>O</td>
<td>64fs</td>
<td>O</td>
<td></td>
</tr>
</tbody>
</table>

Table 5 AK4118’s Audio Data Format (Parallel control mode <Default>)

It is necessary to set DIF1-0 bits of AK4627’s registers and SW3-1 (DIF2), SW3-2 (DIF1), SW3-3 (DIF0) to the same audio data format when AK4627 is on Serial Control Mode.

<table>
<thead>
<tr>
<th>Mode</th>
<th>DIF1</th>
<th>DIF0</th>
<th>SDTO1-2</th>
<th>SDTO1-3</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 0 0 0</td>
<td>24bit, Left justified</td>
<td>20bit, Right justified</td>
<td>(Default)</td>
<td></td>
</tr>
<tr>
<td>1 0 1 0</td>
<td>24bit, Left justified</td>
<td>24bit, Right justified</td>
<td>(Default)</td>
<td></td>
</tr>
<tr>
<td>2 0 0 0</td>
<td>24bit, Left justified</td>
<td>24bit, Left justified</td>
<td>(Default)</td>
<td></td>
</tr>
<tr>
<td>3 1 1 1</td>
<td>24bit, I’S</td>
<td>24bit, I’S</td>
<td>(Default)</td>
<td></td>
</tr>
</tbody>
</table>

Table 6 AK4627’s Audio data formats (Serial control mode)
AK4118 supplies AK4627’s Master Clock with MCKO1.

<table>
<thead>
<tr>
<th>No.</th>
<th>OCKS1</th>
<th>OCKS0</th>
<th>MCKO1</th>
<th>MCKO2</th>
<th>X’tal</th>
<th>fs (max)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>256fs</td>
<td>256fs</td>
<td>256fs</td>
<td>96 kHz</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>256fs</td>
<td>128fs</td>
<td>256fs</td>
<td>96 kHz</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>0</td>
<td>512fs</td>
<td>256fs</td>
<td>512fs</td>
<td>48 kHz</td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>1</td>
<td>128fs</td>
<td>64fs</td>
<td>128fs</td>
<td>192 kHz</td>
</tr>
</tbody>
</table>

(default)

Table 7 AK4118’s Master Clock Frequency Select (Stereo mode)

<table>
<thead>
<tr>
<th>Mode</th>
<th>CM1</th>
<th>CM0</th>
<th>PLL</th>
<th>X’tal</th>
<th>Clock source</th>
<th>SDTO</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0</td>
<td>0</td>
<td>ON</td>
<td>ON</td>
<td>PLL</td>
<td>RX</td>
</tr>
<tr>
<td>1</td>
<td>0</td>
<td>1</td>
<td>OFF</td>
<td>ON</td>
<td>X’tal</td>
<td>DAUX</td>
</tr>
<tr>
<td>2</td>
<td>1</td>
<td>0</td>
<td>ON</td>
<td>ON</td>
<td>PLL</td>
<td>RX</td>
</tr>
<tr>
<td>3</td>
<td>1</td>
<td>1</td>
<td>ON</td>
<td>ON</td>
<td>X’tal</td>
<td>DAUX</td>
</tr>
</tbody>
</table>

ON: Oscillation (Power-up), OFF: STOP (Power-Down)

Table 8 AK4118’s Clock Operation Mode select

■ Other jumper pins set up

1. JP81 (GND) : Connection between AGND and DGND.
   OPEN : AGND and DGND are separated on the board. <Default>
   SHORT : AGND and DGND are connected on the board. <Default>

2. JP11 (RX3) : Digital input connector selection for AK4118.
   OPT : Optical connector (PORT1) is used, except when Quad Speed Mode for DAC evaluation.
   BNC : BNC Jack (J1) is used. <Default>

3. JP12 (TX) : Digital output connector selection for AK4118.
   OPT : Optical connector (PORT2) is used.
   BNC : BNC Jack (J2) is used. <Default>

4. JP15 (MCLK_SEL): This jumper pin is fixed to SHORT. <Default>

5. JP65 (SDTI4) : This jumper pin is not used. <Default>

■ The function of the toggle SW


■ The indication content for LED

[LE1] Monitor DZF1 pin of the AK4627.

About zero detection of AK4627, please refer to Page 23 of AK4627’s datasheet.
■ Serial Control

The AK4627 can be controlled via the printer port (parallel port) of IBM-AT compatible PC. Connect PORT3 (CTRL) with PC by 10 wire flat cable packed with the AKD4627-A.

Figure 2 Connect of 10 wire flat cable

The AK4627 supports 3-wire serial control mode and I2C-bus control mode (fast-mode, max : 400kHz). Please set the jump pins: JP61 (SEL1), JP63 (SEL2) and JP62 (SEL3), referred to (2) Serial Control Mode.

<table>
<thead>
<tr>
<th>Mode</th>
<th>Chip Address</th>
<th>SW2-7 (CAD1)</th>
<th>SW2-8 (CAD0)</th>
<th>R/W</th>
</tr>
</thead>
<tbody>
<tr>
<td>3-wire</td>
<td>00</td>
<td>0</td>
<td>0</td>
<td>Write only (default)</td>
</tr>
<tr>
<td></td>
<td>01</td>
<td>0</td>
<td>1</td>
<td>Write only</td>
</tr>
<tr>
<td></td>
<td>10</td>
<td>1</td>
<td>0</td>
<td>Write only</td>
</tr>
<tr>
<td></td>
<td>11</td>
<td>1</td>
<td>1</td>
<td>Write only</td>
</tr>
<tr>
<td>I2C</td>
<td>00</td>
<td>0</td>
<td>0</td>
<td>R/W</td>
</tr>
<tr>
<td></td>
<td>01</td>
<td>0</td>
<td>1</td>
<td>R/W</td>
</tr>
<tr>
<td></td>
<td>10</td>
<td>1</td>
<td>0</td>
<td>R/W</td>
</tr>
<tr>
<td></td>
<td>11</td>
<td>1</td>
<td>1</td>
<td>R/W</td>
</tr>
</tbody>
</table>

Table 9 Select Interface and Chip Address
Analog Input/Output Circuits

1. Analog Input Circuits

Figure 3  AKD4627-A Analog Input Circuits
2. Analog Output Circuits

Figure 4 AKD4627-A Analog Output Circuits
Evaluation Board and Control Soft Settings

1. Set an evaluation board properly.
2. Connect the evaluation board to an IBM PC/AT compatible PC by a 10 wire flat cable. Be aware of the direction of the 10pin header. When running this control soft on the Windows 2000/XP, the driver which is included in the CD must be installed. Refer to the “Driver Control Install Manual for AKM Device Control Software” for installing the driver. When running this control soft on the windows 95/98/ME, driver installing is not necessary. This control soft does not support the Windows NT.
3. Continue the evaluation by following the process below.

Operation Screen

1. Start up the control program following the process above.

The operation screen is shown below.
Operation Overview

Register map and testing tool can be controlled by this control soft. These controls are selected by upper tabs.

Buttons which are frequently used such as register initializing button “Write Default”, are located outside of the switching tab window. Refer to the “Dialog Boxes” for details of each dialog box setting.

1. [Port Reset]: For when connecting to USB I/F board (AKDUSBIF-A)
   Click this button after the control soft starts up when connecting USB I/F board (AKDUSBIF-A).
2. [Write Default]: Register Initializing
   When the device is reset by a hardware reset, use this button to initialize the registers.
3. [All Write]: Executing write commands for all registers displayed.
4. [All Read]: Executing read commands for all registers displayed.
5. [Save]: Saving current register settings to a file.
6. [Load]: Executing data write from a saved file.
7. [All Reg Write]: “All Reg Write” dialog box is popped up.
8. [Data R/W]: “Data R/W” dialog box is popped up.
9. [Sequence]: “Sequence” dialog box is popped up.
10. [Sequence(File)]: “Sequence(File)” dialog box is popped up.
11. [Read]: Reading current register settings and display on to the Register area (on the right of the main window). This is different from [All Read] button, it does not reflect to a register map, only displaying hexadecimal.
1. [REG]: Register Map

This tab is for a register writing and reading.

Each bit on the register map is a push-button switch.
Button Down indicates “H” or “1” and the bit name is in red (when read only it is in deep red).
Button Up indicates “L” or “0” and the bit name is in blue (when read only it is in gray).

The registers which is not defined in the datasheet are indicated as “---”.

<table>
<thead>
<tr>
<th>Address</th>
<th>Example Indication: // Button UP is &quot;H&quot; or &quot;1&quot;// Button DOWN is &quot;L&quot; or &quot;0&quot;// Blanks are invalid.</th>
</tr>
</thead>
<tbody>
<tr>
<td>00H</td>
<td>---</td>
</tr>
<tr>
<td>01H</td>
<td>---</td>
</tr>
<tr>
<td>02H</td>
<td>ATI7 ATI6 ATI5 ATI4 ATI3 ATI2 ATI1 ATI0</td>
</tr>
<tr>
<td>03H</td>
<td>ATI7 ATI6 ATI5 ATI4 ATI3 ATI2 ATI1 ATI0</td>
</tr>
<tr>
<td>04H</td>
<td>ATI7 ATI6 ATI5 ATI4 ATI3 ATI2 ATI1 ATI0</td>
</tr>
<tr>
<td>05H</td>
<td>ATI7 ATI6 ATI5 ATI4 ATI3 ATI2 ATI1 ATI0</td>
</tr>
<tr>
<td>06H</td>
<td>ATI7 ATI6 ATI5 ATI4 ATI3 ATI2 ATI1 ATI0</td>
</tr>
<tr>
<td>07H</td>
<td>ATI7 ATI6 ATI5 ATI4 ATI3 ATI2 ATI1 ATI0</td>
</tr>
<tr>
<td>08H</td>
<td>--- 1 DEMA1 DEMA0 DEMB1 DEMB0 DEMC1 DEMC0</td>
</tr>
<tr>
<td>09H</td>
<td>--- --- ATS1 ATS0 PDDA3 PDDA2 PDDA1 RSTN</td>
</tr>
<tr>
<td>0AH</td>
<td>--- D2FM3 D2FM2 D2FM1 D2FM0 PAVRN PAADN PAADAN</td>
</tr>
<tr>
<td>0BH</td>
<td>--- --- --- --- --- PDAD2 PDAD1</td>
</tr>
</tbody>
</table>
[Write]: Data Writing Dialog

It is for when changing two or more bits on the same address at the same time.

Click [Write] button located on the right of the each corresponded address for a pop-up dialog box.

When checking the checkbox, the register will be “H” or “1”, when not checking the register will be “L” or “0”. Click [OK] to write setting value to the registers, or click [Cancel] to cancel this setting.

[Read]: Data Read

Click [Read] button located on the right of the each corresponded address to execute register reading.

After register reading, the display will be updated regarding to the register status. Button Down indicates “H” or “1” and the bit name is in red (when read only it is in deep red). Button Up indicates “L” or “0” and the bit name is in blue (when read only it is in gray).

Please be aware that button statuses will be changed by Read command.
2. [Tool]: Testing Tools

This tab screen is for evaluation testing tool. Click buttons for each testing tool.
Dialog Boxes

1. [All Reg Write]: All Register Write dialog box

Click [All Reg Write] button in the main window to open register setting files. Register setting files saved by [SAVE] button can be applied.

[Open (left)]: Selecting a register setting file (*.akr).
[Write]: Executing register writing.
[Write All]: Executing all register writings.
   Writings are executed in descending order.
[Help]: Help window is popped up.
[Save]: Saving the register setting file assignment. The file name is “*.mar”.
[Open (right)]: Opening a saved register setting file assignment “*.mar”.
[Close]: Closing the dialog box and finish the process.

*Operating Suggestions
(1) Those files saved by [Save] button and opened by [Open] button on the right of the dialog “*.mar” should be stored in the same folder.
(2) When register settings are changed by [Save] button in the main window, re-read the file to reflect new register settings.
2. [Data R/W]: Data R/W Dialog Box

Click the [Data R/W] button in the main window for data read/write dialog box. Data write is available to specified address.

Address Box: Input data address in hexadecimal numbers for data writing.
Data Box: Input data in hexadecimal numbers.
Mask Box: Input mask data in hexadecimal numbers.
   This is “AND” processed input data.

[Write]: Writing to the address specified by “Address” box.

[Read]: Reading from the address specified by “Address” box.
   The result will be shown in the Read Data Box in hexadecimal numbers.

[Close]: Closing the dialog box and finish the process.
   Data writing can be cancelled by this button instead of [Write] button.

*The register map will be updated after executing [Write] or [Read] commands.
3. [Sequence]: Sequence Dialog Box

Click [Sequence] button to open register sequence setting dialog box. Register sequence can be set in this dialog box.

Sequence Setting

Set register sequence by following process bellow.
(1) Select a command
   Use [Select] pull-down box to choose commands. Corresponding boxes will be valid.
   < Select Pull-down menu >
   - No_use: Not using this address
   - Register: Register writing
   - Reg(Mask): Register writing (Masked)
   - Interval: Taking an interval
   - Stop: Pausing the sequence
   - End: Finishing the sequence

(1) Input sequence
   [Address]: Data address
   [Data]: Writing data
   [Mask]: Mask
   [Data] box data is ANDed with [Mask] box data. This is the actual writing data.
   When Mask = 0x00, current setting is hold.
   When Mask = 0xFF, the 8bit data which is set in the [Data] box is written.
   When Mask = 0x0F, lower 4bit data which is set in the [Data] box is written.
   Upper 4bit is hold to current setting.
Valid boxes for each process command are shown below.

- No_use: None
- Register: [Address], [Data], [Interval]
- Reg(Mask): [Address], [Data], [Mask], [Interval]
- Interval: [Interval]
- Stop: None
- End: None

**Control Buttons**

The function of Control Button is shown below.

[Start]: Executing the sequence

[Help]: Opening a help window
[Save]: Saving sequence settings as a file. The file name is “*.aks”.
[Open]: Opening a sequence setting file “*.aks”.
[Close]: Closing the dialog box and finish the process.

**Stop of the sequence**

When “Stop” is selected in the sequence, processing is paused and it starts again when [Start] button is clicked. Restarting step number is shown in the “Start Step” box. When finishing the process until the end of sequence, “Start Step” will return to “1”.

The sequence can be started from any step by writing the step number to the “Start Step” box. Write “1” to the “Start Step” box and click [Start] button, when restarting the process from the beginning.
4. [Sequence(File)]: Sequence Setting File Dialog Box

Click [Sequence(File)] button to open sequence setting file dialog box. Those files saved in the “Sequence setting dialog” can be applied in this dialog.

[Open (left)]: Opening a sequence setting file (*.aks).
[Start]: Executing the sequence setting.
[Start All]: Executing all sequence settings. Sequences are executed in descending order.

[Help]: Pop up the help window.
[Save]: Saving sequence setting file assignment. The file name is “*.mas”.
[Open(right)]: Opening a saved sequence setting file assignment “*.mas”.
[Close]: Closing the dialog box and finish the process.

*Operating Suggestions
(1) Those files saved by [Save] button and opened by [Open] button on the right of the dialog “*.mas” should be stored in the same folder.
(2) When “Stop” is selected in the sequence the process will be paused and a pop-up message will appear. Click “OK” to continue the process.
### MEASUREMENT RESULTS

#### 1) ADC part

**[Measurement condition]**
- **Measurement unit**: Audio Precision, System two, Cascade
- **MCLK**: 512 fs at 48 kHz, 256 fs at 96 kHz
- **BICK**: 64 fs
- **fs**: 48 kHz, 96 kHz
- **BW**: 20 Hz to 20 kHz at fs=48 kHz, 20 Hz to 40 kHz at 96 kHz
- **Bit**: 24 bit
- **Power Supply**: AVDD=DVDD=TVDD=5V
- **Interface**: DIT (AK4118)
- **Temperature**: Room

#### a) Single-ended Inputs

**fs=48kHz**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input signal</th>
<th>Measurement filter</th>
<th>LIN1</th>
<th>RIN1</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>S/(N+D)</td>
<td>1kHz, -0.5dBFS</td>
<td>20kHz LPF</td>
<td>96.9</td>
<td>96.5</td>
<td>dB</td>
</tr>
<tr>
<td>DR</td>
<td>1kHz, -60dBFS</td>
<td>20kHz LPF</td>
<td>99.8</td>
<td>99.9</td>
<td>dB</td>
</tr>
<tr>
<td>S/N</td>
<td>No signal</td>
<td>20kHz LPF</td>
<td>99.9</td>
<td>100.1</td>
<td>dB</td>
</tr>
</tbody>
</table>

**fs=96kHz**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input signal</th>
<th>Measurement filter</th>
<th>LIN1</th>
<th>RIN1</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>S/(N+D)</td>
<td>1kHz, -0.5dBFS</td>
<td>40kHz LPF</td>
<td>93.1</td>
<td>93.0</td>
<td>dB</td>
</tr>
<tr>
<td>DR</td>
<td>1kHz, -60dBFS</td>
<td>40kHz LPF</td>
<td>98.0</td>
<td>98.1</td>
<td>dB</td>
</tr>
<tr>
<td>S/N</td>
<td>No signal</td>
<td>40kHz LPF</td>
<td>98.1</td>
<td>98.1</td>
<td>dB</td>
</tr>
</tbody>
</table>

#### b) Differential Inputs

**fs=48kHz**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input signal</th>
<th>Measurement filter</th>
<th>LIN1 ±</th>
<th>RIN1 ±</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>S/(N+D)</td>
<td>1kHz, -0.5dBFS</td>
<td>20kHz LPF</td>
<td>98.3</td>
<td>97.4</td>
<td>dB</td>
</tr>
<tr>
<td>DR</td>
<td>1kHz, -60dBFS</td>
<td>20kHz LPF</td>
<td>100.2</td>
<td>100.3</td>
<td>dB</td>
</tr>
<tr>
<td>S/N</td>
<td>No signal</td>
<td>20kHz LPF</td>
<td>100.4</td>
<td>100.4</td>
<td>dB</td>
</tr>
</tbody>
</table>

**fs=96kHz**

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input signal</th>
<th>Measurement filter</th>
<th>LIN1 ±</th>
<th>RIN1 ±</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>S/(N+D)</td>
<td>1kHz, -0.5dBFS</td>
<td>40kHz LPF</td>
<td>95.9</td>
<td>95.5</td>
<td>dB</td>
</tr>
<tr>
<td>DR</td>
<td>1kHz, -60dBFS</td>
<td>40kHz LPF</td>
<td>98.4</td>
<td>98.5</td>
<td>dB</td>
</tr>
<tr>
<td>S/N</td>
<td>No signal</td>
<td>40kHz LPF</td>
<td>98.4</td>
<td>98.5</td>
<td>dB</td>
</tr>
</tbody>
</table>
2) DAC part

[Measurement condition]
- Measurement unit: Audio Precision, System two, Cascade
- MCLK: 512fs at 48kHz, 256fs at 96kHz, 128fs at 192kHz
- BICK: 64fs
- fs: 48kHz, 96kHz, 192kHz
- BW: 20Hz~20kHz at fs=48kHz, 20Hz~40kHz at 96kHz, 20Hz~40kHz at 192kHz
- Bit: 24bit
- Power Supply: AVDD=DVDD=TVDD=5V
- Interface: DIR (AK4118)
- Temperature: Room

fs=48kHz

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input signal</th>
<th>Measurement filter</th>
<th>LOUT1</th>
<th>ROUT1</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>S/(N+D)</td>
<td>1kHz, 0dBFS</td>
<td>20kHz Brick-wall LPF</td>
<td>101.5</td>
<td>100.4</td>
<td>dB</td>
</tr>
<tr>
<td>DR</td>
<td>1kHz, -60dBFS</td>
<td>20kHz Brick-wall LPF</td>
<td>103.3</td>
<td>103.2</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A-weighted</td>
<td>105.7</td>
<td>105.7</td>
<td>dB</td>
</tr>
<tr>
<td>S/N</td>
<td>No signal</td>
<td>20kHz Brick-wall LPF</td>
<td>103.3</td>
<td>103.1</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A-weighted</td>
<td>105.8</td>
<td>105.7</td>
<td>dB</td>
</tr>
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</table>

fs=96kHz

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input signal</th>
<th>Measurement filter</th>
<th>LOUT1</th>
<th>ROUT1</th>
<th>Units</th>
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<tbody>
<tr>
<td>S/(N+D)</td>
<td>1kHz, 0dBFS</td>
<td>40kHz Brick-wall LPF</td>
<td>99.3</td>
<td>98.1</td>
<td>dB</td>
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<tr>
<td>DR</td>
<td>1kHz, -60dBFS</td>
<td>40kHz Brick-wall LPF</td>
<td>100.6</td>
<td>100.5</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A-weighted</td>
<td>105.6</td>
<td>105.5</td>
<td>dB</td>
</tr>
<tr>
<td>S/N</td>
<td>No signal</td>
<td>40kHz Brick-wall LPF</td>
<td>100.6</td>
<td>100.5</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A-weighted</td>
<td>105.6</td>
<td>105.5</td>
<td>dB</td>
</tr>
</tbody>
</table>

fs=192kHz

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Input signal</th>
<th>Measurement filter</th>
<th>LOUT1</th>
<th>ROUT1</th>
<th>Units</th>
</tr>
</thead>
<tbody>
<tr>
<td>S/(N+D)</td>
<td>1kHz, 0dBFS</td>
<td>40kHz Brick-wall LPF</td>
<td>98.3</td>
<td>97.6</td>
<td>dB</td>
</tr>
<tr>
<td>DR</td>
<td>1kHz, -60dBFS</td>
<td>40kHz Brick-wall LPF</td>
<td>100.5</td>
<td>100.6</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A-weighted</td>
<td>105.6</td>
<td>105.5</td>
<td>dB</td>
</tr>
<tr>
<td>S/N</td>
<td>No signal</td>
<td>40kHz Brick-wall LPF</td>
<td>100.7</td>
<td>100.5</td>
<td>dB</td>
</tr>
<tr>
<td></td>
<td></td>
<td>A-weighted</td>
<td>105.6</td>
<td>105.5</td>
<td>dB</td>
</tr>
</tbody>
</table>
1.1.1 ADC (fs=48kHz, Single-ended Inputs)

FFT (Input=-0.5 dB, fin=1kHz)

FFT (Input=-60 dB, fin=1kHz)
THD + N vs. Input Level (fin=1kHz)

THD + N vs. Input Frequency (Input=-0.5dBr)
Linearity (fin=1kHz)

Frequency Response (Input Level=-0.5dBr)
Crosstalk (Input Level=-0.5dBr)
1.1.2 ADC (fs=96kHz, Single-ended Inputs)

FFT (Input=-0.5dB, fin=1kHz)

FFT (Input=-60dB, fin=1kHz)
FFT (Noise floor)
THD + N vs. Input Level (fin=1kHz)

THD + N vs. Input Frequency (Input Level=-0.5dBr)
Linearity (fin=1kHz)

Frequency Response (Input Level=-0.5dBr)
Crosstalk
1.2.1 ADC (fs=48kHz, Differential Inputs)

FFT (Input=-0.5dBr, fin=1kHz)

FFT (Input=-60dBr, fin=1kHz)
FFT (noise floor)
THD + N vs. Input Level (fin=1kHz)

THD + N vs. Input Frequency (Input=-0.5dBr)
Linearity (fin=1kHz)

Frequency Response (Input Level=-0.5dBr)
Crosstalk (Input Level=-0.5dB)

Hz

dB

-60

-70

-80

-90

-100

-110

-120

-130

-140

-150

-160

20 50 100 200 500 1k 2k 5k 10k 20k
1.2.2 ADC (fs=96kHz, Differential Inputs)

FFT (Input=-0.5dBm, fin=1kHz)

FFT (Input=-60dBm, fin=1kHz)
FFT (Noise floor)
THD + N vs. Input Level (fin=1kHz)

THD + N vs. Input Frequency (Input Level=-0.5dBr)
Linearity (fin=1kHz)

Frequency Response (Input Level=-0.5dBr)
Crosstalk (Input Level=-0.5dBu)
2.1 DAC (fs=48kHz)

**FFT (Input=0dBFS, fin=1kHz)**

**FFT (Input=-60dBFS, fin=1kHz)**
THD + N vs. Input Level (fin=1kHz)

THD + N vs. Input Frequency (Input=0dBFS)
Linearity (fin=1kHz)

Frequency Response (Including external RC filter)
2.2 DAC (fs=96kHz)

FFT (Input=0dBFS, fin=1kHz)

FFT (Input=0dBFS, fin=1kHz, Notch on)
FFT (Input=-60dBFS, fin=1kHz)

FFT (Noise floor)
FFT (Out-of-band noise)
THD + N vs. Input Level (fin=1kHz)

THD + N vs. Input Frequency (Input=0dBFS)
Linearity (fin=1kHz)

Frequency Response (Including external RC filter)
Crosstalk (Input=0dBFS)
2.3 DAC (fs=192kHz)

FFT (Input=0dBFS, fin=1kHz)

FFT (Input=0dBFS, fin=1kHz, Notch on)
FFT (Input=-60dBFS, fin=1kHz)

FFT (Noise floor)
FFT (Out-of-band noise)
THD + N vs. Input Level (fin=1kHz)

THD + N vs. Input Frequency (Input=0dBFS)
Linearity (fin=1kHz)

Frequency Response (Including external RC filter)
Crosstalk (Input=0dBFS)
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Revision History

<table>
<thead>
<tr>
<th>Date</th>
<th>Manual Revision</th>
<th>Board Revision</th>
<th>Reason</th>
<th>Contents</th>
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<td>2010/08/09</td>
<td>KM102000</td>
<td>0</td>
<td>First Edition</td>
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<tr>
<td>2012/04/19</td>
<td>KM102001</td>
<td>1</td>
<td>Change</td>
<td>Circuit pattern were changed.</td>
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